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| <b>Term:</b> | L3 same (copier or image forming) |
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| <u>L4</u>                                    | L3 same (copier or image forming)   | 77                         | <u>L4</u>                               |
| <u>L3</u>                                    | l2 same (paper or sheet) near2 feeding with (path or direction)                     | 372                        | <u>L3</u>                               |
| <u>L2</u>                                    | supply near2 (sheet or paper or recording medium) with (tray or cartridge or unit)  | 8537                       | <u>L2</u>                               |
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| AND                  | <input type="text"/> | in         | All Fields |
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**OPTION 2**

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(paper <or> sheet) <sentence> (feed <or>  
feeding) <sentence> (tray <or> path <or>  
direction)

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Kushibiki, J.; Ohashi, Y.; Ono, Y.; Sasamata, T.;  
 Ultrasonics, Ferroelectrics and Frequency Control, IEEE Transactions on  
 Volume 49, Issue 7, July 2002 Page(s):905 - 914

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#### 2. Two layers position control system of a manipulator using feed forward control

Faress, K.N.S.; El-Hagry, M.M.T.;  
 Electrical and Computer Engineering, 2001. Canadian Conference on  
 Volume 1, 13-16 May 2001 Page(s):661 - 665 vol.1

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#### 3. Electronic beam steering using a varactor-tuned impedance surface

Sievenpiper, D.; Schaffner, J.; Loo, B.; Tandon, G.; Harold, R.; Pikulski, J.; Garcia, R.  
 Antennas and Propagation Society International Symposium, 2001. IEEE  
 Volume 1, 8-13 July 2001 Page(s):174 - 177 vol.1

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#### 4. Space Interferometry Mission System testbed-3: external metrology inversion

Alvarez-Salazar, O.S.; Azizi, A.;  
 Aerospace Conference, 2004. Proceedings. 2004 IEEE  
 Volume 3, 6-13 March 2004 Page(s):

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